(Name or UUN) focused on part 2 (Vision) of the coursework and (Name or UUN) focused on part 3 (Control) of the coursework. We both helped each other in our respective parts. Part 4 was worked on by both members.

Github link: <https://github.com/Ziemniok352/IVR-Assignment/>

**Part 2**

(Add plots and answers here)

**Forward Kinematics 3.1**

|  |  |  |
| --- | --- | --- |
| **Joint angles (θ1,θ2,θ3,θ4)** | **Est. end-effector from image(x,y,z)** | **Est. end-effector from Forward Kinematics(x,y,z)** |
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Comment on accuracy here

**Closed-loop Control 3.2**

Plot 3 graphs comparing x,y,z pos of end effector with x,y,z of target